# Global thrust faulting on the Moon and the influence of tidal stresses

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#### **ABSTRACT**

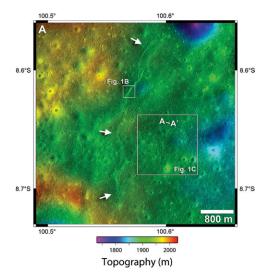
Lunar Reconnaissance Orbiter Camera images reveal a vast, globally distributed network of over 3200 lobate thrust fault scarps, making them the most common tectonic landform on the Moon. Based on their small scale and crisp appearance, crosscutting relations with small-diameter impact craters, and rates of infilling of associated small, shallow graben, these fault scarps are estimated to be younger than 50 Ma and may be actively forming today. The non-random distribution of the scarp orientations is inconsistent with isotropic stresses from late-stage global contraction as the sole source of stress. We propose that tidal stresses contribute significantly to the current stress state of the lunar crust. Orbital recession stresses superimposed on stresses from global contraction with the addition of diurnal tidal stresses result in non-isotropic compressional stress and thrust faults consistent with lobate scarp orientations. The addition of diurnal tidal stresses at apogee result in peak stresses that may help trigger coseismic slip events on currently active thrust faults on the Moon.

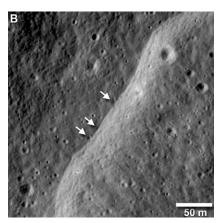
#### INTRODUCTION

Tectonic landforms described as lobate scarps are common on the terrestrial planets (Watters, 2003; Watters et al., 2009; Watters and Schultz, 2010). The morphology, crosscutting relations, reversals in vergence, segment linkage, and modeling all suggest that lobate scarps express

contraction of crustal materials and are formed by thrust faults (Schultz, 1976; Binder, 1982; Watters and Johnson, 2010; Watters et al., 2010). Some lobate scarp thrust faults on Mercury and Mars are on a scale with the largest thrust fault structures on Earth (e.g., the Wind River Mountains, Wyoming, USA), with over a kilometer of relief and hundreds of kilometers in length (Watters, 2003; Watters et al., 2009). Lunar lobate scarps, in contrast, are relatively small-scale landforms, typically <10 km in length with only tens of meters of relief (Fig. 1A) (Watters and Johnson, 2010; Watters et al., 2010; Banks et al., 2012). Fault dislocation modeling constrains the maximum depth of the associated thrust faults to be within the upper kilometer of the lunar megaregolith (Williams et al., 2013).

In Apollo mission–era studies, the number and global distribution of lunar scarps were unknown (Watters et al., 2010) because the high-resolution Lunar Orbiter and Apollo Panoramic Camera photographs were limited in coverage to only a portion of the lunar equatorial zone (Schultz, 1976; Binder, 1982). Currently, over one million images of the lunar surface have been acquired by the Lunar Reconnaissance Orbiter Camera (LROC) Wide Angle Camera (WAC) and Narrow Angle Cameras (NACs) (Robinson et al., 2010). The pixel scale of NAC images (0.5–2.0 m/pixel) is ideal for the detection of the small-scale land-forms (Watters et al., 2010; Banks et al., 2012). We show the global distribution and orientations of the emerging population of lunar thrust fault scarps and investigate causal stresses by comparing predicted tidal





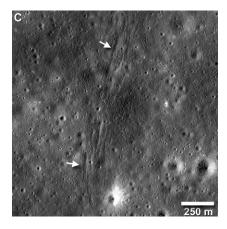


Figure 1. A: Digital elevation model of Pasteur scarp generated using Lunar Reconnaissance Orbiter Camera (LROC) Narrow Angle Camera (NAC) stereo images (frames M1113517026 and M1113502820). Pasteur scarp (white arrows) is located in nearside highlands (~8.6°S, 100.6°E), and has maximum relief of ~20 m. Located ~1.2 km from the scarp face are small-scale graben (see C). Digital elevation model has a horizontal spatial scale of 4 m/pixel (NAC stereo images have resolution of ~1 m/pixel) and vertical precision of ~0.5 m (see the Data Repository [see footnote 1]). Topographic profile across a graben (A–A') is shown in Figure DR1 (see footnote 1). Elevations are referenced to sphere of 1,737,400 m radius. B: Segment of Pasteur scarp crosscutting small-diameter impact craters. Craters ~4–7 m in diameter (white arrows) are crosscut or disturbed by the lobate scarp. Craters this small are estimated to be no older than 800 Ma. Figure location is shown in A. LROC NAC frame M1113517026. C: Graben (white arrows) associated with highland Pasteur scarp. Pasteur graben are oriented subparallel to scarp face and extend for ~1.5 km with the largest ~300 m in length and ~20–30 m wide, while some graben have widths of <10 m. Shallow graben formed in regolith would be expected to disappear in <50 m.y. Figure location is shown in A. LROC NAC frame M1113517026.

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stresses in combination with global contraction due to interior cooling. (Further information is available in the GSA Data Repository<sup>1</sup>.)

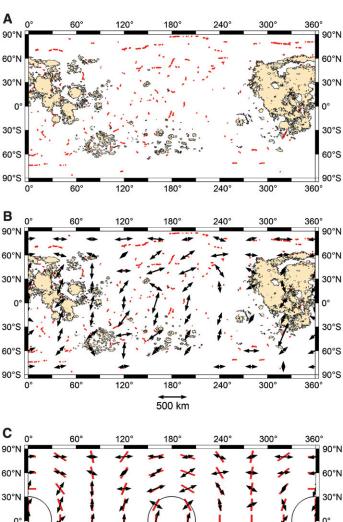
# AGE AND SPATIAL DISTRIBUTION OF LUNAR LOBATE SCARPS

Lobate scarps are thought to be relatively young landforms due to the lack of superposed relatively large-diameter (>400 m) impact craters, their generally crisp morphology, and crosscutting relations with small-diameter impact craters (<50 m in diameter) (Fig. 1B) (Binder, 1982; Watters et al., 2010). Impact craters with diameters of <50 m are estimated to be no older than 800 ± 15 Ma (Copernican age) (Trask, 1971; Stöffler and Ryder, 2001). Small-scale extensional troughs or graben with depths as shallow as 1-2 m are locally found in back-limb areas of the scarps and are likely a consequence of flexural bending (Fig. 1C; Fig. DR1 in the Data Repository) (Watters et al., 2012). Shallow troughs in the lunar regolith are estimated to fill in at a rate of  $5 \pm 3$  cm/m.y., based on analysis of boulder tracks (Arvidson et al., 1975). Thus, shallow graben formed in regolith are expected to disappear in <50 m.y., consistent with the interpretation that lobate scarps are young tectonic landforms (Watters et al., 2012). Young faults may also be consistent with recorded lunar seismic activity. Although the majority of the recorded moonquakes were deep within the interior, triggered in part by tidal stresses (Weber et al., 2009), 28 were shallow (<100 km depth; see Nakamura et al., 1979; Watters and Johnson, 2010).

LROC NAC images obtained to date cover >70% of the lunar surface with complete coverage of the polar regions (within 20° latitude of the poles) except in permanently shadowed regions. The locations of lobate scarps identified in an ongoing survey of these images were digitized directly from map-projected, 2 m pixel-scale NAC mosaics and 100 m pixel-scale WAC monochrome mosaics. NAC images with large incidence angles (>50°; see the Data Repository) are optimum for identifying and digitizing the lobate scarps. Over 3200 scarps were digitized, with each scarp divided into segments with uniform orientations and minimum segment lengths of ~200 m (Fig. 2) (see the Data Repository). Lobate scarps are globally distributed, confirming predictions based on earlier, sparse surveys (Watters et al., 2010; Banks et al., 2012). Their occurrence at all latitudes on both the nearside and farside makes them the most common and broadly distributed tectonic landform on the Moon. A small fraction of lobate scarps are found in mare basalts (~3\% of mapped scarps), but they occur primarily in the lunar highlands where they are the dominant tectonic landform (Fig. 2A). Some lobate scarps (~4% of those mapped) occur in highlands at the margins of the mare units. One explanation for the disproportionately small number of lobate scarps in maria may be the preference for wrinkle ridges, more complex contractional features, to form in the multilayered mare basalts (see Watters and Johnson, 2010). Although the longest individual scarps typically reach maximum lengths up to only a few tens of kilometers, clusters of scarps in linear and curvilinear patterns may extend for several hundred kilometers (Fig. 2A).

#### DISTRIBUTION OF SCARP ORIENTATIONS

The orientations of the fault scarps were evaluated by sampling the digitized segments in areas with dimensions of  $40^\circ$  longitude  $\times$   $20^\circ$  latitude. The median orientations were plotted and scaled by the total length of the structures within the sampled areas (Fig. 2B). The overall pattern reveals that the orientations of many scarps are broadly north-south at low to mid-latitudes and east-west at high latitudes. This could be due to observational bias where features oriented perpendicular to the local illumination direction are expected to be preferentially enhanced, because at the equator the illumination direction is east or west and at the poles the illu-



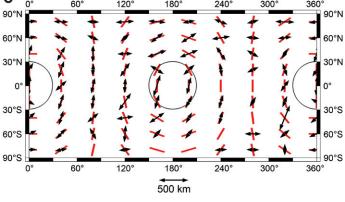


Figure 2. A: Map of digitized locations of lobate scarps on the Moon. Over 3200 lunar scarps (red) have been mapped. Mare basalt units are shown in tan. B: Plot of median orientations of lobate scarps (black double arrows) sampled in areas with dimensions of 40° longitude × 20° latitude and scaled by total length of structures in sampled areas. Each digitized scarp consists of a polyline, a connected series of linear segments. Orientation of each segment is used to determine median orientation of scarps in sampled area (see Table DR1 [see footnote 1]). Mare basalt units are shown in tan. C: Orientations of predicted faults (red lines) due to combination of recession stresses, diurnal tidal stresses at apogee, and global contraction plotted with median orientations of lobate scarps (black double arrows). Predicted fault trajectories correspond to the orthogonal to the most compressive stress directions. Sub-Earth and anti-Earth regions are shown by black circles.

mination direction is north or south. However, significant deviations from north-south orientations are common at the low to mid-latitudes (Fig. 2B). Even at high latitudes ( $\pm 60^{\circ}$  and poleward) where the dominant orientations are more east-west, north-south-oriented scarps are found (see the Data Repository; Fig. DR2). Thus, while the influence of illumination bias cannot be disregarded, the pattern of orientations of the lobate scarps is not

<sup>&</sup>lt;sup>1</sup>GSA Data Repository item 2015287, description of the digital elevation model, mapping of the tectonic landforms, tidal stress models, and supporting figures, is available online at www.geosociety.org/pubs/ft2015.htm, or on request from editing@geosociety.org or Documents Secretary, GSA, P.O. Box 9140, Boulder, CO 80301, USA.

dominated by this effect. Other influences, however, may locally affect the orientation of the scarps, most notably the nearside mare basins. Lobate scarps associated with mare commonly occur near the contact between the mare basalts and highland material with orientations that parallel the basin margins (Watters and Johnson, 2010). This proximity suggests that mechanical heterogeneities and boundary effects introduced by the mare basins influenced the orientations of the lobate scarps at basin margins on the nearside.

#### ORIGIN OF STRESSES

Thermal history models for an initially totally molten Moon (Binder and Gunga, 1985; Binder, 1986; Pritchard and Stevenson, 2000) or an early Moon with a near-surface magma ocean (Solomon and Head, 1979, 1980; Solomon, 1986) both predict late-stage global contraction. The early cessation of basin-related flexural extension from loading by mare basalts, not long after the end of the period of late heavy bombardment (ca. 3.8 Ga) (Lucchitta and Watkins, 1978; Boyce, 1976; Hiesinger et al., 2000, 2003), may be due to the superposition of compressional stresses from global contraction, marking a transition in the Moon's thermal history where interior cooling resulted in a shift from net expansion to net contraction (Solomon and Head, 1979, 1980; Solomon, 1986). The magnitude of compressional stress from a small sample of the young thrust faults was previously estimated to be <10 MPa (Watters et al., 2010; Watters and Johnson, 2010), consistent with low levels of post-late heavy bombardment compressional stress predicted by magma ocean thermal models (Solomon and Head, 1979, 1980; Solomon, 1986). Using the population of fault scarps described in this global study, the contractional strain is estimated to be equivalent to a radius change of ~25 m corresponding to isotropic stresses of ~2 MPa (see Watters and Johnson, 2010). This is a minimum stress because the entire population of fault scarps has yet to be mapped. Based on strength envelopes for near-surface lunar regolith, stresses of ~2-7 MPa are sufficient for shallow thrust faults (upper few hundred meters depth) to develop (see Williams et al., 2013).

In the absence of other influences, global contraction will result in horizontally isotropic compressional stresses. Such a stress field is expected to form a population of thrust faults that are more or less uniformly distributed but with random orientations. However, the distribution of orientations of mapped lobate scarps is non-random (Fig. 2) (weighted vector mean ~9.0°, circular standard deviation  $54.3^\circ$ , n = 51,614 digitized segments), and thus their orientations are not consistent with global contraction as the sole source of compressional stress. Mechanical inhomogeneities introduced by the nearside mare basins and perhaps by heavily degraded rims of ancient farside basins (Frey, 2011) may play a role in locally orienting the stresses, but the distribution of orientations suggests that other global-scale stresses have influenced the formation of the thrust faults.

#### TIDAL STRESSES

Relaxation of early lunar tidal and rotational bulges from despinning and orbital recession may have been a source of global stress. Melosh (1980) examined these effects, and the predicted stresses are expected to result in contraction and north-south—oriented thrust faults in the region in and around the sub-Earth and anti-Earth points, a system of strike-slip faults at low to mid-latitudes outside sub- and anti-Earth areas, and extension and east-west—oriented normal faulting in the polar regions (Melosh, 1980; Collins et al., 2010). In addition to the absence of evidence for strike-slip and poleward normal faults, tidal despinning likely peaked early in the Moon's evolution. Continued, slow orbital recession, however, contributes significantly to the current stress state of the Moon, and the magnitude of this stress is a function of  $h_2$ , the Love number defining the vertical displacement in response to a gravitational potential, and the distance the satellite has receded over a period of time (Melosh, 1980; Collins et al., 2010) (see the Data Repository). On short time scales, recession

stresses are small. However, if recession stresses have accumulated over a long period, much greater than the age of the thrust faults, they may be considerably larger. Also,  $h_2$  has likely significantly decreased with time to its present value (~0.04; Mazarico et al., 2014; Williams and Boggs, 2015) as the lunar interior has cooled and increased in rigidity. Thus, the maximum recession stresses at the sub- and anti-Earth points could be ~20–40 kPa for an  $h_2$  of 0.04–0.08 (as much as twice the present value) for a period of recession of 1.2 b.y. (see Fig. DR3).

Another component of the current state of stress of the Moon is Earthraised solid body tides (Watters et al., 2010). The Moon is a tidally locked (synchronous orbit) satellite with nonzero orbital eccentricity. Thus, as the Moon moves from perigee (closest distance) to apogee (farthest distance), diurnal tidal stresses are induced by the Earth. The amplitude of the diurnal tidal budge is small, on the order of only ~10-20 cm as determined using Lunar Orbiter Laser Altimeter (LOLA) ranging (Mazarico et al., 2014). The maximum diurnal stress is proportional to  $3EeH/R_m$  where e is the orbital eccentricity,  $R_{\rm m}$  is the radius of the Moon, E is Young's modulus, and H is the static tidal bulge amplitude, which is related to  $h_2$ (Collins et al., 2010; Murray and Dermott, 1999). The magnitude of the diurnal stress is low (maximum of ≤5 kPa) compared to those from orbital recession and global contraction. While diurnal stresses are compressional in the region around the sub-Earth and anti-Earth points at apogee, the stresses oscillate with the Moon's orbital position, becoming extensional at the same locations at perigee.

The current stress state of the lunar crust thus consists of at least three global components: diurnal tidal stress  $\sigma$ , orbital recession stress  $\sigma$ , and global contraction  $\sigma_a$ . Orbital recession and diurnal tidal stresses, although relatively small, superimposed on stresses from global contraction will result in a net non-isotropic compressional stress field  $\sigma_n$  where  $\sigma_n >> \sigma_n$  $> \sigma_{\rm r}$ . The non-isotropic compressional stress  $\sigma_{\rm r}$  is expected to result in thrust faulting with preferred orientations (Fig. 2C; Fig. DR5). Although the ratio of the maximum stress from global contraction to the stress from orbital recession is large (up to ~100 depending on the assumed time scale and  $h_2$  value; see Fig. DR3), the small non-isotropic stresses may control thrust fault orientations in regions that are otherwise mechanically homogeneous. As a test of this hypothesis, the orientation of each mapped fault segment was compared to the local orientation of the principal axis of most compressive stress calculated from three general models: orbital recession, despinning, and orbital recession with added diurnal tides. If the tidal stresses are influencing the fault population, the expected faults would be close to perpendicular to the local axis of most compressive stress. The predicted fault orientations from all three models are generally in good agreement with the observed orientations of the lobate scarps and are markedly different from a simulated population of faults with random orientations from isotropic contraction (Fig. 3). None of the models is a perfect fit, with a significant fraction (36%-40%) of the faults more than 45° from the expected local orientation. With such a small organizing stress superimposed on isotropic contraction, such deviations should be expected due to a variety of influences (see the Data Repository). Overall, the pattern of preferred orientations of the population of young thrust fault scarps is best accounted for by recession stresses added to the stress due to global contraction (Fig. 3). Recession stresses combined with the diurnal stress at apogee result in an almost equally good fit (Fig. 3). Stresses due to recession do not change with orbital position, thus it is the combination of recession and contraction stresses that dominate throughout the Moon's orbit, with peak compressional stresses reached by the addition of diurnal stresses at apogee.

Because the magnitude of  $\sigma_n$  is the greatest at apogee when diurnal and recession stresses are most compressive, coseismic slip on the thrust faults may preferentially occur during this time. If the population of thrust faults is still active, the occurrence of shallow seismic events may be greater when the Moon is at apogee. This hypothesis can be tested when the International Lunar Network is deployed.

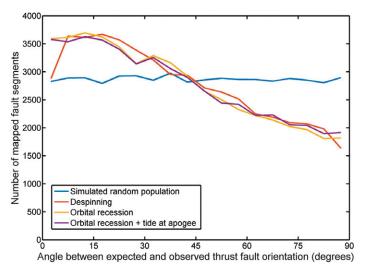


Figure 3. Agreement between observed faults and expected local thrust fault orientations due to different stress models. Fault segments at 0° on plot are orthogonal to local direction of most compressive stress, and at 90° they are parallel to most compressive stress. Red line shows expected orientations for decrease in spin rate; yellow line shows expected orientations for lowering of tidal and rotational distortions as the Moon recedes from Earth; purple line shows stresses from recession added to diurnal tidal stress at apogee (see the Data Repository [see footnote 1]). For reference, blue line shows simulated fault population with same total number of fault segments but with random orientations, as may be expected under an isotropic stress field. Angular differences are sampled in 5° bins.

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# Geology

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### **Digital Elevation Model**

5 A digital elevation model (DEM) for the Pasteur scarp (Fig. 1) was derived from 6 LROC NAC stereo pairs (Burns et al., 2012). These stereo pairs were initially processed 7 with the U.S. Geologic Survey's Integrated Software for Imagers and Spectrometers 8 (ISIS) and the terrain was derived using the BAE Systems SOCET SET® commercial 9 photogrammetry system (Miller and Walker, 1993, 1995) with custom libraries provided 10 by the USGS Astrogeology Science Center in Flagstaff, AZ. Profiles obtained from the 11 DEM show that the small, narrow graben in the back-scarp terrain are only a few meters 12 in depth at most. A topographic profile across one of the widest graben (~45 m) shows 13 that it is  $\sim 1.5$  to 2 m deep with a relatively flat floor (Fig. DR1).

### **Lobate Scarp Mapping**

The locations of lobate scarps are digitized as polylines (a connected series of linear segments) at a scale of up to 1:20,000 in an equirectangular projection in equatorial regions (between 60°N and 60°S). Digitization was completed on a 100m/pixel LROC WAC monochrome (643 nm) mosaic and local area NAC mosaics sampled at 2 m/pixel. NAC images with incidence angles between 50° and 80° were optimum for identifying and digitizing the lobate scarps. Lobate scarps are often found in complexes or clusters consisting of groups of individual scarps. Individual scarps were divided into segments with uniform trends to best approximate the overall orientation and were digitized along the base of the scarp face. The smallest digitized segments were ~200 m in length.

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Image parameters important for the detection of tectonic landforms are incidence angle, solar azimuth (illumination direction at the surface), and pixel scale. Incidence angle is defined as the angle between the local solar vector and the surface normal. Images obtained with low incidence angles (near local noon) are optimal for revealing subtle reflectance variations (compositional or maturity differences) while images with large incidence angle images (near terminator) are optimal for revealing subtle topographic relief (e.g. tectonic landforms that have low relief and surface slopes of only a few degrees). The illumination azimuth (compass direction towards sub-solar point) is equally important to the detection of tectonic landforms because linear features with orientations parallel to the solar azimuth may not be apparent (fewer shadows are being cast). The orientations of the small-scale lobate scarps mapped in this study are dominantly N-S at low to mid-latitudes and E-W at high latitudes. We considered that this preferred orientation could be due to observational bias where features oriented perpendicular to the local illumination direction are expected to be preferentially enhanced, since at the equator the illumination direction is east or west and at the poles the illumination direction is north or south. However, a plot of the mapped lobate scarp segments with latitude shows that in addition to the ~20,000 fault scarp segments with roughly N-S orientations ( $\pm 30^{\circ}$ ) at low to mid-latitudes ( $0^{\circ}$  to  $\pm 60^{\circ}$ ), there are also ~7,900 segments with orientations of  $\pm 60^{\circ}$  to  $\pm 90^{\circ}$  (roughly E–W) at low to mid-latitudes (Fig. DR2). At high latitudes (greater than  $\pm 60^{\circ}$ ), there are ~4,300 scarp segments with roughly E-W orientations along with ~1,800 segments with N-S orientations (Fig. DR2). Further, a comparison of histograms of scarp segment lengths with E-W and N-S orientations indicates no preference toward segments with greater lengths in the detection

- of the scarps. Thus, while the effect of Sun azimuth bias cannot be discounted, the large
- range of orientations at all latitudes suggests that it has not controlled our results.

#### **Orbital Recession and Diurnal Stress Models**

- The stresses resulting from orbital recession were modeled using equations from
- Melosh (1977, 1980). The maximum stresses at the sub- and anti-Earth points (at the tidal
- 52 axis) are given by

$$\sigma_{\theta\theta} = \frac{11}{3} E\left(\frac{1+\nu}{5+\nu}\right) h_2 \frac{M}{m} r^3 \left(\frac{1}{(a_o)^3} - \frac{1}{a^3}\right)$$
(1)

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$$\sigma_{\varphi\varphi} = \frac{17}{3} E\left(\frac{1+\nu}{5+\nu}\right) h_2 \frac{M}{m} r^3 \left(\frac{1}{(a_o)^3} - \frac{1}{a^3}\right)$$
(2)

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- where  $\sigma_{\theta\theta}$  and  $\sigma_{\phi\phi}$  are the longitudinal (N-S) and latitudinal (E-W) stress components
- respectively, E is Young's Modulus, v is Poisson's ratio, M is the mass of the Earth, m is
- 59 the mass of the Moon, r is the radius of the Moon, and  $a_o$  is the starting orbital radius and
- a is the current orbital radius. The magnitude of the orbital recession stresses are very
- sensitive to  $h_2$  and change in orbital radius a  $a_o$  determined by the period of recession
- 62 (Fig. DR3).
- The Earth-raised diurnal stresses on the Moon were modeled. At apogee, diurnal
- stresses are compressional in the region around the sub-Earth and anti-Earth points (Fig.
- DR4). However, diurnal stresses oscillate with the Moon's orbital position becoming
- 66 extensional at the same locations at perigee. Modeled orbital recession stresses plus
- 67 diurnal stress at apogee are superimposed on a background isotropic stress of 2 MPa

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68	resulting from global contraction (Fig. DR5). The predicted fault trajectories correspond
69	to the orientation orthogonal to the most compressive stress directions of the recession
70	stresses. Deviations between the predicted and observed orientations may be due to a
71	variety of influences that include mechanical inhomogeneities associated with impact
72	basins. Significant deviations may also occur where the differential stress, the difference
73	in magnitude between the most and least compressive, are low. This is generally the case
74	at high latitudes (Fig. DR5).
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77	Figure DR1. Topographic profile across the one of the widest graben in the back-scarp
78	terrain of the Pasteur scarp. Profile location is shown Fig. 1. Vertical exaggeration is
79	~11:1. Elevations are referenced to a sphere of 1,737,400 m.
80	
81	Figure DR2. Plot of orientations of all digitized lobate scarp segments as a function of
82	latitude. In the plot, $0^\circ$ azimuth is N-S and $\pm 90^\circ$ azimuth is E-W. The plot shows there
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	are a large number of segments with orientations between $\pm 30^{\circ}$ (roughly N-S)
84	are a large number of segments with orientations between $\pm 30^\circ$ (roughly N-S) particularly at the low to mid-latitudes. However, the plot also shows a very large number
<ul><li>84</li><li>85</li></ul>	
	particularly at the low to mid-latitudes. However, the plot also shows a very large number
85	particularly at the low to mid-latitudes. However, the plot also shows a very large number of segments with roughly N-S orientations ( $\pm 30^{\circ}$ ) and E-W orientations ( $\pm 60^{\circ}$ to $\pm 90^{\circ}$ ) at
85 86	particularly at the low to mid-latitudes. However, the plot also shows a very large number of segments with roughly N-S orientations ( $\pm 30^{\circ}$ ) and E-W orientations ( $\pm 60^{\circ}$ to $\pm 90^{\circ}$ ) at
<ul><li>85</li><li>86</li><li>87</li></ul>	particularly at the low to mid-latitudes. However, the plot also shows a very large number of segments with roughly N-S orientations ( $\pm 30^{\circ}$ ) and E-W orientations ( $\pm 60^{\circ}$ to $\pm 90^{\circ}$ ) at all latitudes.

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92 Figure DR4. Orientations of principal stresses due to Earth-raised diurnal tides at apogee. 93 Compressional stress components are show by red lines and reach a maximum of 5 kPa. 94 Extensional stress components are shown by blue lines. Diurnal stresses are modeled 95 with no latitude or longitude offset from the sub-Earth point. Sub-Earth and anti-Earth 96 regions shown with black circles. 97 98 Figure DR5. Orientation of the maximum principal stress due to orbital recession with 99 diurnal stresses at apogee and global contraction superimposed. Orbital recession stresses were estimated using  $h_2 = 0.08$ , recession period =  $1.2 \times 10^9$  yrs, average orbit radius = 100  $3.847 \times 10^8$  km, orbit radius at apogee =  $4.054 \times 10^8$  km. The red dashes are the directions 101 102 of the most compressive stress. Contours are in kPa with black being most compressive 103 and blue being least compressive stress. 104 105 REFERENCES CITED 106 Burns K.N., Speyerer, E.J., Robinson, M.S., Tran, T., Rosiek, M.R., Archinal, B.A., 107 Howington-Kraus, E., and the LROC Science Team, 2012, Digital elevation models 108 and derived products from LROC NAC stereo observations: International Archives of 109 the Photogrammetry, Remote Sensing and Spatial Information Sciences, XXXIX-B4, 110 XXII ISPRS Congress. 111 Miller, S.B., and Walker, A.S., 1993, Further developments of Leica Digital Photo-112 grammetric Systems by Helava: ACSM/ASPRS Ann. Convention Exposition, Tech. 113 Papers, v. 3, p. 256–263.

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**Table DR1. Orientation Vectors of Lobate Scarps** 

Longitude	Latitude	Mean	Median	Weighted	Standard	Sum of
(deg.)	(deg.)			Mean	Deviation	Lengths (km)
-160	-60	-8.44	21.04	-38.22	115.35	22.76
-160	-40	-10.83	23.98	-22.26	98.35	24.02
-160	-20	13.28	29.55	42.28	127.32	46.36
-160	0	13.82	13.24	14.87	103.37	167.55
-160	20	38.23	45.74	43.09	91.72	102.92
-160	40	38.93	62.75	43.61	96.61	226.2
-160	60	26.88	38	28.11	92.94	187.22
-160	80	19.42	41.5	28.67	90.28	31.72
-120	-80	51.87	69.92	49.23	77.39	29.3
-120	-40	-17.02	10.51	-14.43	81.5	53.3
-120	-20	8.39	18.22	13.35	103.21	67.08
-120	20	-27.64	-6.56	-23.18	115.9	33.43
-120	40	-20.52	-28.07	-19.46	97.09	139.64
-120	60	38.98	73.87	14.77	83.83	189.76
-120	80	-11.96	-23.76	-6.77	100.43	74.52
-80	-80	-37.58	-82.81	-13.16	86	36.78
-80	-60	48.01	90	47.47	103.23	130.5
-80	-20	-4.02	29.57	-13.68	86.69	7.88
-80	20	52.64	63.49	35.49	122.96	29.75
-80	40	92.94	127.48	89.62	98.95	57.2
-80	60	45.14	100.23	33.01	121.1	52.17
-80	80	7.04	31.28	8	70.89	20.39
-40	-80	1.02	0	1.87	149.56	4.25
-40	-60	44.86	30.46	34.61	115.91	30.07
-40	-40	0.71	17.48	-0.39	99.18	428.56
-40	-20	47.79	21.56	63.7	83.88	21.46
-40	0	49.71	36.53	46.08	100.95	71.29
-40	20	15.56	-18.01	31.81	92.27	56.69
-40	40	-14.78	-155.94	-25.67	166.81	5.08
-40	60	50.86	77.27	44.11	86.94	62.53
-40	80	67.16	100.3	63.94	89.63	218.11
0	-80	17.14	65.24	30.89	96.5	78.66
0	-60	11.03	49.31	1.09	97.05	135.53
0	-40	37.49	41.44	37.6	107.11	130.94
0	-20	57.03	119.92	52.9	113.99	34.66
0	0	1.61	3.8	1.76	115.29	257.69
0	20	14.6	29.72	27.14	110.75	123.15

0	40	1.14	13.05	6.53	112.44	202.2
0	60	36.1	68.23	35.98	106.5	88.85
0	80	23.39	47.7	21.56	83.53	98.83
40	-80	15.04	43.58	14.27	90.91	37.31
40	-60	-16.77	24.57	1.09	109.13	63.49
40	-40	-19.03	14.49	-20.11	102.33	103.56
40	-20	27.37	17.56	29.46	90.97	140.17
40	0	39.54	48.02	47.23	127.99	100.14
40	20	26.39	17.75	22.11	96.1	180.83
40	40	23.41	23.58	22.99	110.09	130.49
40	60	-34.71	-60.88	-35.09	90.27	71.24
40	80	-42.74	-77.99	-33.63	88.01	92.2
80	-60	4.18	-15.56	10.23	139.2	52.15
80	-40	47.27	42.66	50.18	93.72	82.83
80	-20	-7.17	8.78	-1.59	124.97	97.72
80	0	13.73	13.87	2.83	116.9	124.47
80	20	-4.66	4.64	-2.3	127.92	27.21
80	40	-7.27	1.37	-1.49	128.67	154.92
80	60	110.17	131.32	109.81	75.94	31.74
80	80	95.38	105.05	98.42	58.51	21.28
120	-80	-96.01	-128.27	-88.66	86.94	17.95
120	-60	0.16	2.3	-2.81	98.72	152.24
120	-40	60.43	79.45	68.27	92.86	160.53
120	-20	25.25	33.65	23.39	108.42	267.77
120	0	-12.34	4.65	-29.7	114.52	90.3
120	20	26.77	32.72	26.2	125.07	148.84
120	40	65.67	87.43	54.95	76.62	100.22
120	60	6.6	30.42	-19.76	119.76	11.4
120	80	-72.85	-109.89	-81.79	97.53	194.98
160	-60	-0.92	24.11	-0.45	69.27	20.73
160	-40	42.37	48.33	50.27	97.14	187.2
160	-20	-7.28	15.41	-12.86	124.61	98.21
160	0	20.39	17.21	16.54	117.99	317.86
160	20	62.89	123.86	76	109.57	122.32
160	40	31.87	65.9	28.84	99	243.47
160	60	21.76	32.51	-1.76	85.03	118.83
160	80	-34.92	-62.97	-34.2	95.38	164.71

Longitudes and latitudes give the location centers of sampling areas. North is equal to 0 degrees. The accuracy of mean, median, and weighted mean values for the orientation vectors were check by direct comparison with digitized polylines.



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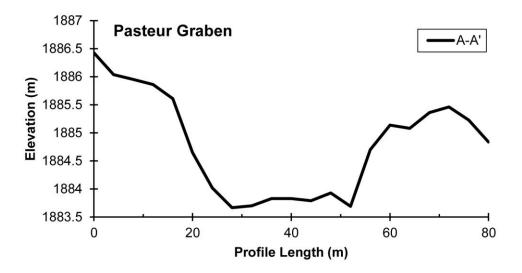
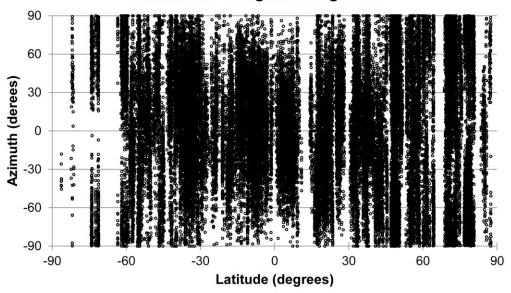


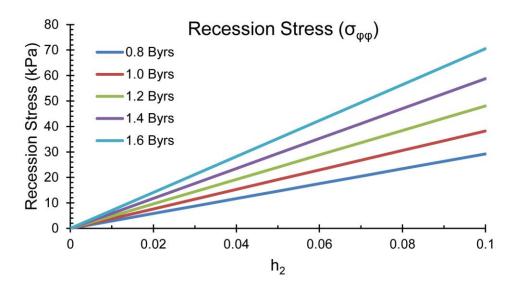
Figure DR1.





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Figure DR2.



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Figure DR3.

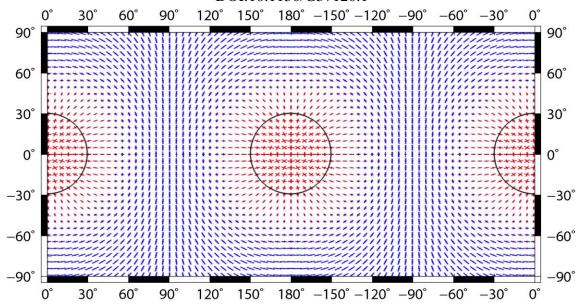


Figure DR4.

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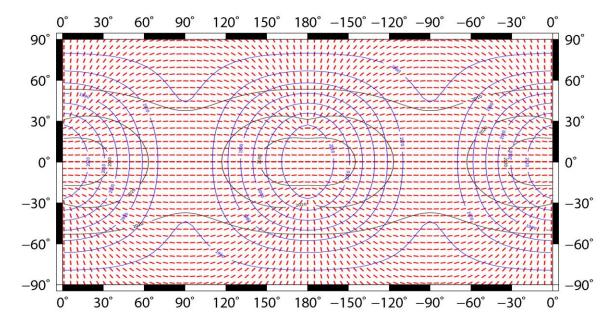


Figure DR5.

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